Ine Frydra Minimally Invasive Surgical System & Nikola Tech

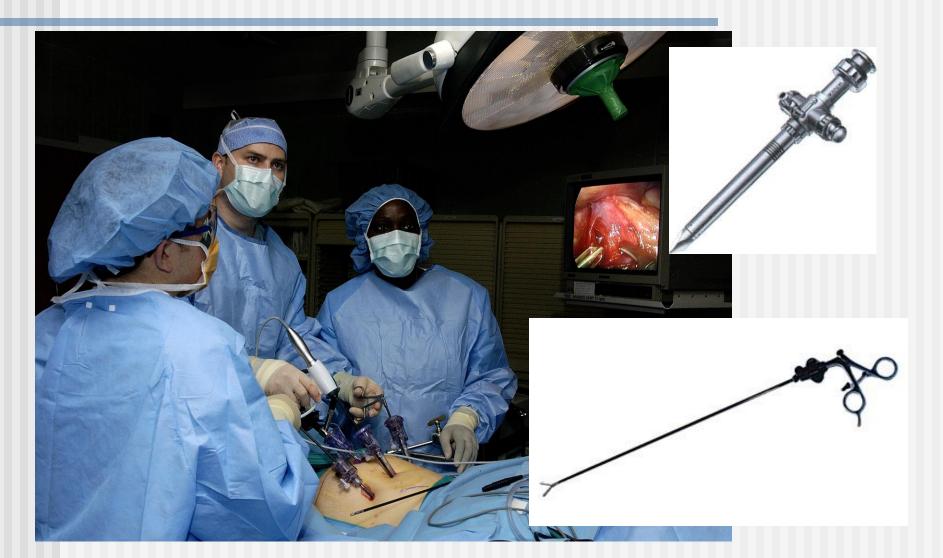
Eric R. Simms, MD Nikola Tech, LLC Tulane University Department of Surgery 2013 LA-SiGMA Research Infrastructure Improvement Symposium Monday, July 29th, 2013



Department of Surgery

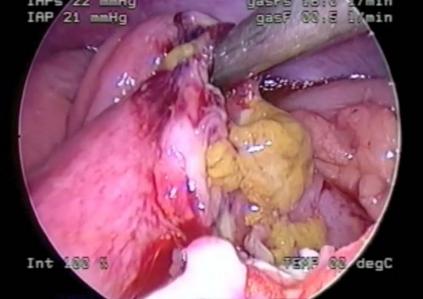


Minimally Invasive Surgery



The Problem

- Time
 - Instrument switching
 - Efficiency
- Safety
 - Economy of motion
 - latrogenic injury



- And in surgery, time is safety
 - Exposure: volatile agents, insufflation, positioning



Dr. Eric R. Simms, MD

Vance



Jordan



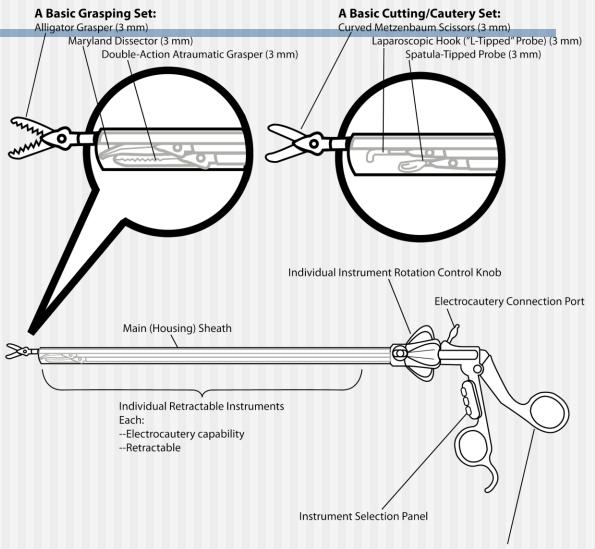


Korndorffer, MD



oseph

The Hydra Minimally Invasive Surgical System:



Dynamic Multifunction Handle

Regents and EPSCoR: OPT-IN Grant

- Proposal submitted: December 2011
- Accepted: February 1, 2012
- Total Budget: \$11,416
- Expenses: Engineering ~\$10,800 Materials ~ \$500
- Project completed: January 2013

The Results of the Project

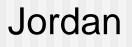
- 3 Iterations of the Hydra MISS
 - 2 Completed prototypes
 - Patent submitted
- Formation of Nikola Tech
- Now applying for NIH Phase I (STTR) grant
 - "Proof of concept"

Nikola Tech, LLC

Dr. Eric R. Simms, MD

Vance









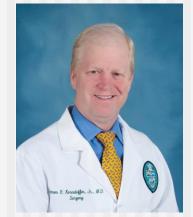


Special Thanks To

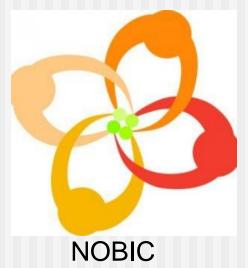




LA-EPSCoR



Dr. James R. Korndorffer, MD



Thank You

